

Computer Organization Test 2

Question 1. (12 points) Select the best answer to the following true-or-false questions:	Circle the correct answer	
a. A jump instruction changes the flow of execution by changing the PC.	True	False
b. Registers are storage locations within the CPU itself.	True	False
c. The main memory (RAM) is faster to access than registers.	True	False
d. Only the AC register in MARIE can be used to hold arbitrary data.	True	False
e. One assembly language instruction generally translates to one machine language instruction.	True	False
f. One high-level language (e.g., Ada, C++, Java, etc.) instruction generally translates to many machine language instruction.	True	False

Question 2. (18 points) Translate the following high-level language code segment to MARIE assembly language. Use the variable labels indicated in the code.

```
SUM = 0
INPUT COUNT
FOR I = 1 TO COUNT DO
    INPUT X
    SUM = SUM + X
END FOR
```

Question 3.

a) (5 points) For the below MARIE program, complete the symbol table.

Symbol	Address of Symbol (in hex.)
END_WHILE	
SUM	
WHILE	
X	

b) (10 points) Translate the given MARIE assembly language into machine language.

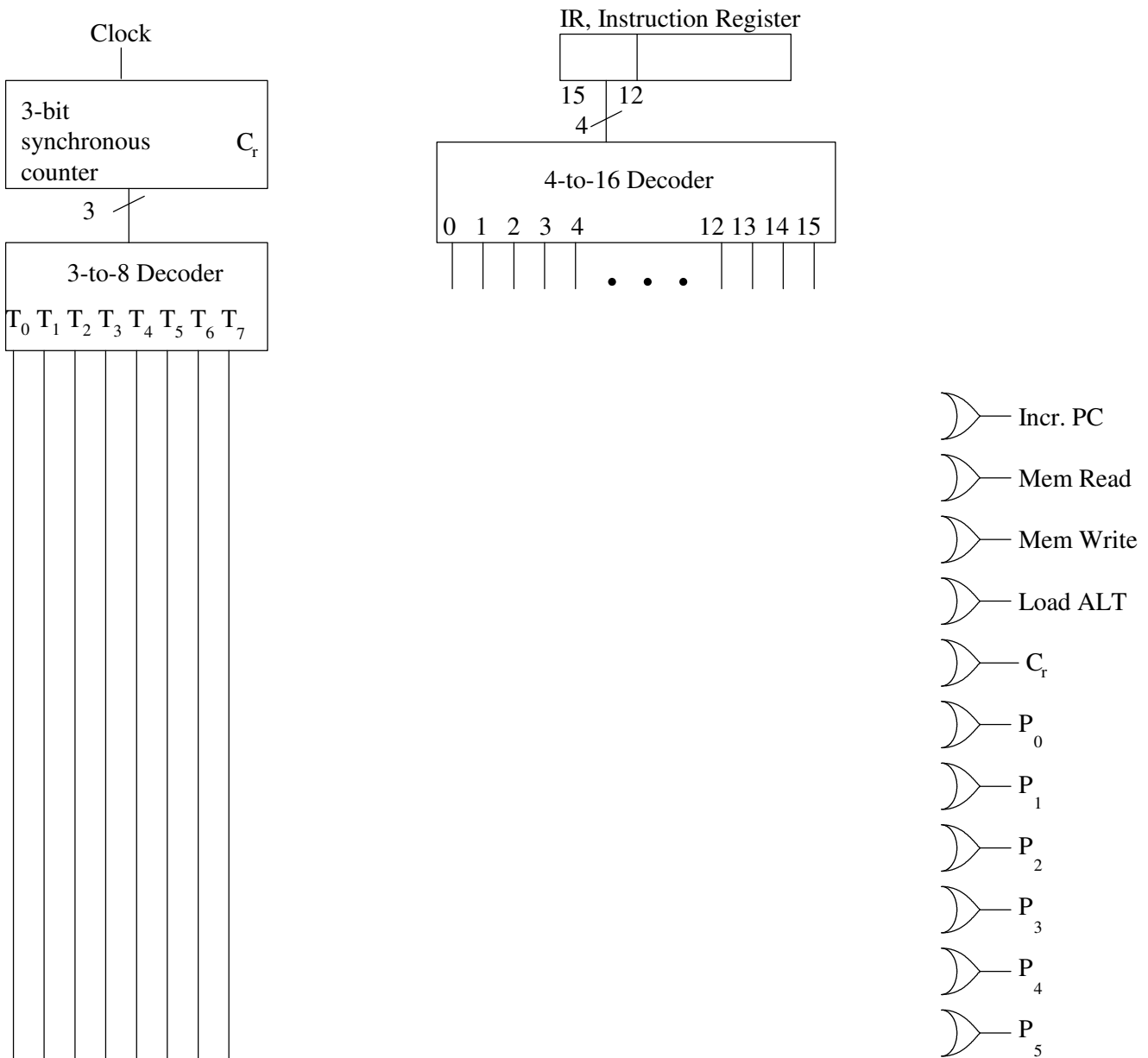
<u>Address</u>	<u>Label</u>	<u>Assembly Language</u>	<u>Machine Language</u> (in hex)
100 ₁₆	WHILE,	LOAD X	
101 ₁₆		SKIPCOND 000	
102 ₁₆		JUMP END_WHILE	
103 ₁₆		ADD SUM	
104 ₁₆		STORE SUM	
105 ₁₆		INPUT	
106 ₁₆		STORE X	
107 ₁₆		JUMP WHILE	
108 ₁₆	END_WHILE,	HALT	
109 ₁₆	X,	DEC 10	
10A ₁₆	SUM,	DEC 0	

c) (10 points) Translate the above MARIE assembly language into high-level language “pseudo” code.

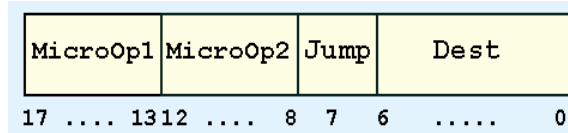
Question 4. (10 points) Which control signals should contain a “1” for each steps in the STORE X instruction?

Step	RTN	Step #	P ₅	P ₄	P ₃	P ₂	P ₁	P ₀	C _r	Incr PC	Mem Read	Mem Write	Load ALT
Fetch	MAR ← PC	T ₀											
	MBR ← M[MAR]	T ₁											
	IR ← MBR	T ₂											
Decode IR[15-12]	PC ← PC + 1	T ₃											
Get operand	MAR ← IR[11-0]	T ₄											
Execute	MBR ← AC	T ₅											
	M[MAR] ← MBR	T ₆											
		T ₇											

Question 5. (10 points) Draw the partial combinational logic of the hardwired control unit to handle the STORE X (opcode 2₁₆) instruction.



Question 6. Recall that the microprogrammed version of MARIE executes a fixed microprogram to perform the fetch-decode-execute cycle. The instruction format for the microinstructions look like:



MicroOp1 encodes the type of register transfer notation (RTN) to perform (e.g., $AC \leftarrow 0$ is 00010_2)

MicroOp2 is used only when decoding the instruction. It contains the binary codes for each instruction to allow comparison to the IR opcode. (Since the MARIE opcodes are only 4-bits long, only bits 12 - 9 are used and bit 8 is unused.)

Jump is a single bit indicating that the value in the **Dest** field is a valid micro-address and should be placed in the microsequencer; if **Jump** is "FALSE" (0), then increment to the next microinstruction.

Table 4.8. Microoperation Codes and Corresponding MARIE RTN (p. 221)

MicroOp Code	Microoperation	MicroOp Code	Microoperation
00000	NOP	01100	$MBR \leftarrow M[MAR]$
00001	$AC \leftarrow 0$	01101	$OutREG \leftarrow AC$
00010	$AC \leftarrow AC - MBR$	01110	$PC \leftarrow IR[11-0]$
00011	$AC \leftarrow AC + MBR$	01111	$PC \leftarrow MBR$
00100	$AC \leftarrow InREG$	10000	$PC \leftarrow PC + 1$
00101	$IR \leftarrow M[MAR]$	10001	If $AC = 00$
00110	$M[MAR] \leftarrow MBR$	10010	If $AC > 0$
00111	$MAR \leftarrow IR[11-0]$	10011	If $AC < 0$
01000	$MAR \leftarrow MBR$	10100	If $IR[11-10] = 00$
01001	$MAR \leftarrow PC$	10101	If $IR[11-10] = 01$
01010	$MAR \leftarrow X$	10110	If $IR[11-10] = 10$
01011	$MBR \leftarrow AC$	10111	If $IR[15-12] = MicroOp2[4-1]$

We need to augment this table to include a few omitted microoperations and because we modified Figure 4.9 to remove the Memory from direct connection to the datapath. The following additional microoperations are used.

MicroOp Code	Microoperation
00101*	$IR \leftarrow MBR$
11000	$AC \leftarrow MBR$

* This microop code is being reused.

a) (10 points) Explain why a microprogrammed control unit is slower than a hardwired control unit?

b) (15 points) Extend the partial microprogram below to include microoperations to decode and implement the execution of the instructions: STORE X and CLEAR. **(Fill in only the bolded boxes)**

Revised Figure 4.21 Partial Microprogram

Part of Cycle	RTN (of MicroOp1)	μ Addr	MicroOp1	MicroOp2	Jump	Dest
Fetch	MAR \leftarrow PC	0	01001	0000	0	0
	MBR \leftarrow M[MAR]	1	01100	0000	0	0
	IR \leftarrow MBR	2	00101	0000	0	0
	PC \leftarrow PC + 1	3	10000	0000	0	0
Decode	If ADD, Jump	4	10111	00110	1	
	If LOAD, Jump	5	10111	00010	1	
("Jump Table")	If STORE, Jump	6	10111	00100	1	
	If SKIPCOND, Jump	7	10111	10000	1	
	If SUBT, Jump	8	10111	01000	1	
	If JUMP, Jump	9	10111	10010	1	
	If ADDI, Jump	10	10111	10110	1	
	If CLEAR, Jump	11	10111	10100	1	
	If JNS, Jump	12	10111	00000	1	
	If JUMPI, Jump	13	10111	11000	1	
	If INPUT, Jump	14	10111	01010	1	
	If OUTPUT, Jump	15	10111	01100	1	
Execute STORE X	If HALT, Jump	16	10111	01110	1	
	MAR \leftarrow IR[11-0]	17				
	MBR \leftarrow AC	18				
Execute CLEAR	M[MAR] \leftarrow MBR	19				
	AC \leftarrow 0	20				
		21				
		22				
		23				
		24				