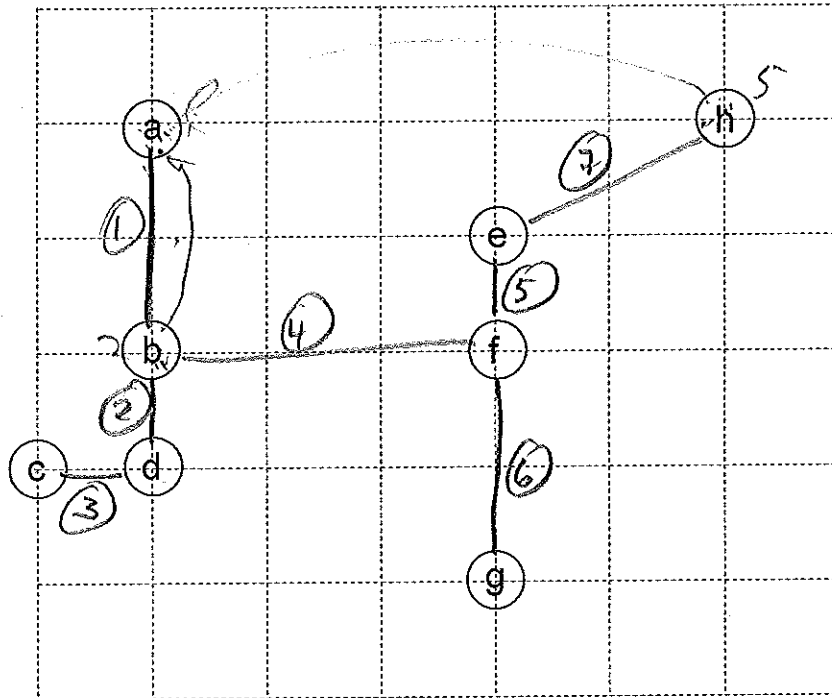


1. Suppose you had a map of settlements on the planet X
(Assume edges could connect all vertices with their Euclidean distances as their costs)



We want to build roads that allow us to travel between any pair of cities. Because resources are scarce, we want the total length of all roads built to be minimal. Since all cities will be connected anyway, it does not matter where we start, but assume we start at "a".

- a) Assuming we start at city "a" which city would you connect first? **b** Why this city?

It is the closest city to 'a'

- b) What city would you connect next to expand your partial road network?

next closest to anything in partial road system

(priority queue / min. heap)

- c) What would be some characteristics of the resulting "graph" after all the cities are connected?

"connected" graph with no cycles \Rightarrow "spanning tree"

- d) Does your algorithm come up with the overall best (globally optimal) result?

bestest / min. spanning tree - MST

2. Prim's algorithm for determining the minimum-spanning tree (MST) of a graph is another example of a *greedy algorithm*. Unlike divide-and-conquer and dynamic programming algorithms, greedy algorithms DO NOT divide a problem into smaller subproblems. Instead a greedy algorithm builds a solution by making a sequence of choices that look best ("locally" optimal) at the moment without regard for past or future choices (no backtracking to fix bad choices).

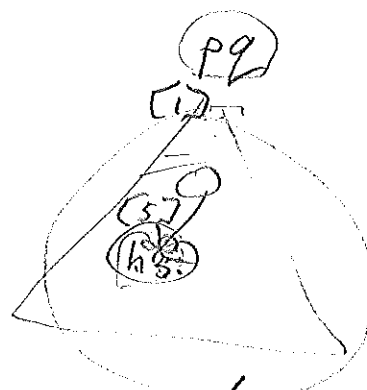
a) What greedy criteria does Prim's algorithm use to select the next vertex and edge to the partial minimum spanning tree?

vertex closest to any vertex in partial MST

b) Consider the textbook's Prim's Algorithm code (Listing 7.12 p. 346) which is incorrect.

```

def prim(G, start):
    pq = PriorityQueue BinHeap() (4) Priority Queue Entry (v.getDistance(), v)
    for v in G:
        v.setDistance(sys.maxsize)
        v.setPred(None)
    start.setDistance(0)
    pq.buildHeap([(v.getDistance(), v) for v in G])
    while not pq.isEmpty():
        currentVert = pq.delMin().getValue()
        for nextVert in currentVert.getConnections():
            newCost = currentVert.getWeight(nextVert) \
                - currentVert.getDistance()
            Priority Queue Entry (newCost, nextVert)
            if v nextVert in pq and newCost < nextVert.getDistance():
                nextVert.setPred(currentVert)
                nextVert.setDistance(newCost)
                pq.decreaseKey(nextVert, newCost)
    
```



c) What is wrong with the code? (Fix the above code.)

- (1) BinHeap instead of PriorityQueue
- (2) newCost calculation - wrong
- (3) "v" should nextVert in if-statement
- (4) pq should a heap of Priority Queue Entry objects
- (5) add `--contains--` to BinHeap + decrease key

3. To avoid "massive" changes to the BinHeap class, it can store PriorityQueueEntry objects:

```

class PriorityQueueEntry:
    def __init__(self, x, y):
        self.key = x distance
        self.val = y vertex

    def getKey(self):
        return self.key

    def getValue(self):
        return self.val

    def setValue(self, newValue):
        self.val = newValue
    
```

```

def __lt__(self, other):
    return self.key < other.key

def __gt__(self, other):
    return self.key > other.key

def __eq__(self, other):
    return self.val == other.val

def __hash__(self):
    return self.key
    
```

a) Update the above Prim's algorithm code to use PriorityQueueEntry objects.

b) Why do the `__lt__` and `__gt__` methods compare key attributes, but `__eq__` compare val attributes?

distance use "<" in pencil

Search -- contains -- by vertex / val part

- c) When used for Prim's algorithm what type of objects are the vals compared by `__eq__`? *Vertex objects*
- d) What changes to the Graph and Vertex classes need to be made? *None?*

- e) Complete the `__contains__` and `decreaseKey` methods.

```

class BinHeap:
    def __init__(self):
        self.heapList = [0]
        self.currentSize = 0
        self._foundIndex = 0
    def buildHeap(self, alist):
        i = len(alist) // 2
        self.currentSize = len(alist)
        self.heapList = [0] + alist[:]
        while (i > 0):
            self.percDown(i)
            i = i - 1
    def percDown(self, i):
        while (i * 2) <= self.currentSize:
            mc = self.minChild(i)
            if self.heapList[i] > self.heapList[mc]:
                tmp = self.heapList[i]
                self.heapList[i] = self.heapList[mc]
                self.heapList[mc] = tmp
            i = mc
    def minChild(self, i):
        if i * 2 + 1 > self.currentSize:
            return i * 2
        else:
            if self.heapList[i*2] < self.heapList[i*2+1]:
                return i * 2
            else:
                return i * 2 + 1
    def percUp(self, i):
        while i // 2 > 0:
            if self.heapList[i] < self.heapList[i//2]:
                tmp = self.heapList[i // 2]
                self.heapList[i // 2] = self.heapList[i]
                self.heapList[i] = tmp
            i = i // 2
    def insert(self, k):
        self.heapList.append(k)
        self.currentSize = self.currentSize + 1
        self.percUp(self.currentSize)
    def delMin(self):
        retval = self.heapList[1]
        self.heapList[1] = self.heapList[self.currentSize]
        self.currentSize = self.currentSize - 1
        self.heapList.pop()
        self.percDown(1)
        return retval
    def isEmpty(self):
        return self.currentSize == 0
    def size(self):
        return self.currentSize
    def __str__(self):
        return str(self.heapList[1:])

```

```

def __contains__(self, value):

```

(i, h)
Priority Queue Entry

```

    for index in range(1, len(self.heapList)):
        if value == self.heapList[index]:
            self._foundIndex = index
            return True
    return False

```

```

def decreaseKey(self, decreasedValue):
    """Precondition: decreasedValue
    in heap already"""

```

if decreasedValue^{not} in self:
raise ValueError(" ")

self.heapList[self._foundIndex]
= decreasedValue
self.percUp(self._foundIndex)