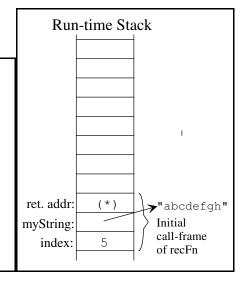
Data Structures - Test 2

Question 1. (10 points) What is printed by the following program?



Question 2. (5 points) Write a recursive Python function to compute the Fibonacci mathematical function, fib(n):

```
fib(0) = 0 (if n is 0)

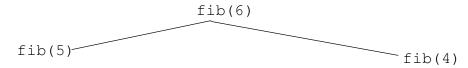
fib(1) = 1 (if n is 1)

fib(n) = fib(n-1) + fib(n-2) for all n values > 1.
```

Output:

def fib(n):

Question 3. a) (7 points) For the above recursive function fib(n), complete the calling-tree for fib(6).



- b) (2 point) What is the value of fib (6)?
- c) (6 point) What would be a better approach to calculating a fibonacci value than the above recursive function?

Question 4. (20 points.) Consider the following insertion sort code which sorts in ascending order.

```
def insertionSort(myList):
    for firstUnsortedIndex in range(1,len(myList)):
        itemToInsert = myList[firstUnsortedIndex]
        testIndex = firstUnsortedIndex - 1

    while testIndex >= 0 and myList[testIndex] > itemToInsert:
        myList[testIndex+1] = myList[testIndex]
        testIndex = testIndex - 1

    myList[testIndex + 1] = itemToInsert
```

- a) What is the purpose of the testIndex >= 0 while-loop comparison?
- b) Consider the modified insertion sort code that eliminates the testIndex >= 0 while-loop comparison.

```
def insertionSortB(myList):
    minIndex = 0
    for testIndex in range(1,len(myList)):
        if myList[testIndex] < myList[minIndex]:
            minIndex = testIndex
    temp = myList[0]
    myList[0] = myList[minIndex]
    myList[minIndex] = temp

for firstUnsortedIndex in range(1,len(myList)):
    itemToInsert = myList[firstUnsortedIndex]
    testIndex = firstUnsortedIndex - 1

    while myList[testIndex] > itemToInsert:
        myList[testIndex+1] = myList[testIndex]
        testIndex = testIndex - 1

    myList[testIndex + 1] = itemToInsert
```

Explain how the **bold code** in the modified insertion sort code allows for the elimination of the testIndex >= 0 while-loop comparison.

Consider the following timing of the above two insertion sorts on lists of 10000 elements.

Initial arrangement of list before sorting	insertionSort - at the top of page	insertionSortB - modified version in middle of the page
Sorted in descending order: 10000, 9999,, 2, 1	14.0 seconds	12.3 seconds
Already in ascending order: 1, 2,, 9999, 10000	0.005 seconds	0.004 seconds
Randomly ordered list of 10000 numbers	7.3 seconds	6.4 seconds

- c) Explain why insertionSortB (modified version in middle of page) out performs the original insertionSort.
- d) In either version, why does sorting the initially ascending order list take less time than sorting the initially descending ordered list?

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Question 5. (25 points) In class we discussed the following bubble sort code which sorts in ascending order (smallest to largest) and builds the sorted part on the right-hand side of the list.

```
def bubbleSort(myList):
    for lastUnsortedIndex in range(len(myList)-1,0,-1):
        alreadySorted = True
    # scan the unsorted part at the beginning of myList
    for testIndex in range(lastUnsortedIndex):
        # if we find two adjacent items out of order, switch them
        if myList[testIndex] > myList[testIndex+1]:
            temp = myList[testIndex]
            myList[testIndex] = myList[testIndex+1]
            myList[testIndex+1] = temp
            alreadySorted = False
    if alreadySorted:
        return
```

For this question write a variation of the above bubble sort that:

- sorts in **descending order** (largest to smallest),
- stops early if the inner-loop makes no swaps, and
- builds the **sorted part on the left-hand side** of the list. Sample picture after running a while:

Sorted Part							Unsorted Part							
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
95	90	80	75	73	68	65	64	25	60	50	15	35	45	10

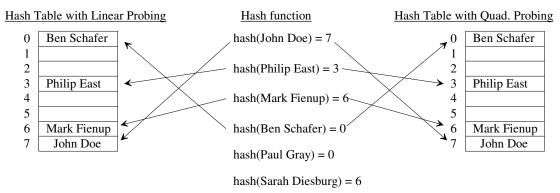
Inner-loop should "bubble" the largest item down the unsorted part from right to left

def BubbleSortVariation(myList):

Question 6. Two common rehashing strategies for open-address hashing are linear probing and quadratic probing:

(quadratic	Check the square of the attempt-number away for an available slot, i.e.,
1	probing	[home address + ((rehash attempt #) 2 +(rehash attempt #) 2] % (hash table size), where the hash table size is
		a power of 2. Integer division is used above

a) (8 points) Insert "Paul Gray" and then "Sarah Diesburg" using Linear (on left) and Quadratic (on right) probing.



b) (7 points) Explain why linear probing suffers from secondary clustering? (Recall that in *secondary clustering* rehash patterns from initially different home addresses merge together)

Question 7. Quick sort general idea is as follows.

- Select a "random" item in the unsorted part as the *pivot*
- Rearrange (*partitioning*) the unsorted items such that:
- Quick sort the unsorted part to the left of the pivot
- Quick sort the unsorted part to the right of the pivot

a) (10 points) Explain how quick sort performs O(n log₂ n) on random data.

Pivot Index					
All items < to Pivot	Pivot Item	All items >= to Pivot			