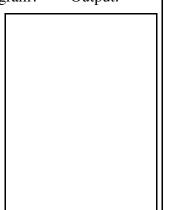
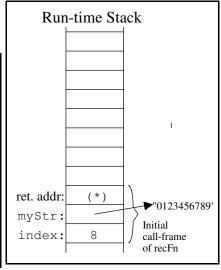
Data Structures - Test 2

Question 1. (10 points) What is printed by the following program? Output:





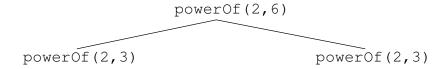
Question 2. Write a recursive Python function to calculate a^n (where n is an integer) based on the formulas:

$$a^0=1$$
, for $n=0$
 $a^1=a$, for $n=1$
 $a^n=a^{n/2}a^{n/2}$, for even $n>1$ (recall we can check for this in Python by $n \ \% \ 2 == 0$)
 $a^n=a^{(n-1)/2}a^{(n-1)/2}a$, for odd $n>1$

a) (12 points) Complete the below powerOf ${\bf recursive}$ function

def powerOf(a, n):

b) (8 points) For the above recursive powerOf function, complete the calling-tree for powerOf (2, 6).



c) (5 points) Suggest a way to speedup the above powerOf function.

Question 3. Consider the following insertion sort which sorts in ascending order, but builds the sorted part on the right.

```
def insertionSort(myList):
    myListLength = len(myList)
    for lastUnsortedIndex in range(len(myList)-2, -1, -1):
        itemToInsert = myList[lastUnsortedIndex]
        testIndex = lastUnsortedIndex + 1
        while testIndex < myListLength and myList[testIndex] < itemToInsert:
            myList[testIndex-1] = myList[testIndex]
            testIndex = testIndex + 1
            myList[testIndex - 1] = itemToInsert</pre>
```

a) (5 points) What is the purpose of the testIndex < myListLength while-loop comparison?

Consider the modified insertion sort code that eliminates the testIndex < myListLength while-loop comparison, but adds the **bold** code.

```
def insertionSortB(myList):
    myList.append(max(myList))
    for lastUnsortedIndex in range(len(myList)-2, -1, -1):
        itemToInsert = myList[lastUnsortedIndex]
        testIndex = lastUnsortedIndex + 1
        while myList[testIndex] < itemToInsert:
            myList[testIndex-1] = myList[testIndex]
            testIndex = testIndex + 1
        myList[testIndex - 1] = itemToInsert
        myList[testIndex - 1] = itemToInsert
        myList.pop()</pre>
```

b) (5 points) Explain how the **bolded** code in the modified insertion sort code above allows for the elimination of the testIndex < myListLength while-loop comparison.

Consider the following timing of the above two insertion sorts on lists of 10000 elements.

Initial arrangement of list before sorting	insertionSort - at the top of page	insertionSortB - modified version in middle of the page
Sorted in descending order: 10000, 9999,, 2, 1	14.1 seconds	12.6 seconds
Already in ascending order: 1, 2,, 9999, 10000	0.004 seconds	0.004 seconds
Randomly ordered list of 10000 numbers	7.3 seconds	6.5 seconds

c) (5 points) Explain why insertionSortB (modified version in middle of page) out performs the original insertionSort.

d) (5 points) In either version, why does sorting the randomly order list take about halve the time of sorting the initially descending ordered list?

Question 4. In class we discussed the following bubble sort code which sorts in ascending order (smallest to largest) and builds the sorted part on the right-hand side of the list, i.e.:

```
scan unsorted part
from left to right

Unorted Part

Sorted Part
```

```
def bubbleSort(myList):
    for lastUnsortedIndex in range(len(myList)-1,0,-1):
        # scan the unsorted part at the beginning of myList
        for testIndex in range(lastUnsortedIndex):

        # if we find two adjacent items out of ascending order, then switch them
        if myList[testIndex] > myList[testIndex+1]:
            temp = myList[testIndex]
            myList[testIndex] = myList[testIndex+1]
            myList[testIndex+1] = temp
```

(20 points) For this question write a variation of the above bubble sort that:

- sorts in **descending order** (largest to smallest)
- builds the sorted part on the left-hand side of the list, i.e.,

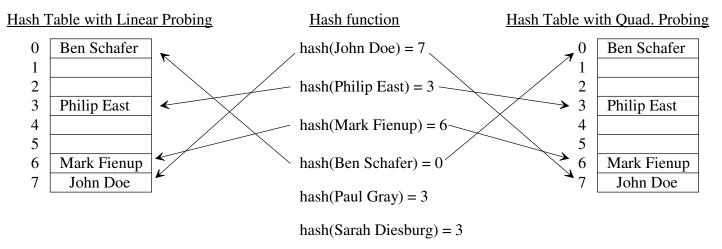
	scan unsorted part from right to left
Sorted Part	Unsorted Part

def bubbleSortVariation(myList):

Question 5. Recall the common rehashing strategies we discussed for open-address hashing:

Strategy	Description	
1 *	Check the square of the attempt-number away for an available slot, i.e.,	
	[home address + ((rehash attempt #) 2 +(rehash attempt #) 2 /2] % (hash table size), where the hash table size	
	a power of 2. Integer division is used above	

a) (8 points) Insert "Paul Gray" and then "Sarah Diesburg" using Linear (on left) and Quadratic (on right) probing.



b) (7 points) Explain why both linear and quadratic probing both suffer from primary clustering?

Question 6. (10 points) The general idea of *Quick sort* is as follows:

- Select a "random" item in the unsorted part as the *pivot*
- Rearrange (*partition*) the unsorted items as shown in diagram on right:
- Quick sort the unsorted part to the left of the pivot
- Quick sort the unsorted part to the right of the pivot

Explain why the worst-case performance is $O(n^2)$.

Pivot Index				
All items < to Pivot	Pivot Item	All items >= to Pivot		