Name:\_

The microprogrammed version of MARIE executes a fixed microprogam to perform the fetch-decode-execute cycle. The instruction format for the microinstructions could look like:



**MicroOp1** encodes the type of register transfer notation (RTN) to perform (e.g., AC  $\leftarrow 0$  is 00010<sub>2</sub>)

MicroOp2 contains the binary codes for each instruction to allow comparison to the IR opcode.

**Jump** is a single bit indicating that the value in the **Dest** field is a valid micro-address and should be placed in the microsequencer; if **Jump** is "FALSE" (0), then increment to the next microinstruction.

MicroOp MicroOp Microoperation Microoperation Code Code 00000 NOP 01100  $MBR \leftarrow M[MAR]$ 00001 01101  $AC \leftarrow 0$  $OutREG \leftarrow AC$ 00010  $AC \leftarrow AC - MBR$ 01110  $PC \leftarrow IR[11-0]$ 00011 01111  $AC \leftarrow AC + MBR$  $PC \leftarrow MBR$ 00100  $AC \leftarrow InREG$ 10000  $PC \leftarrow PC + 1$ If AC = 0000101 10001  $IR \leftarrow M[MAR]$ If AC > 000110 10010  $M[MAR] \leftarrow MBR$ If AC < 000111 10011  $MAR \leftarrow IR[11-0]$ If IR[11-10] = 0001000 10100  $MAR \leftarrow MBR$ 01001 10101 If IR[11-10] = 01 $MAR \leftarrow PC$ If IR[11-10] = 1001010 10110  $\max \leftarrow x$ If IR[15-12] = 01011 10111  $MBR \leftarrow AC$ MicroOp2[4-1]

Table 4.8. Microoperation Codes and Corresponding MARIE RTN (p. 221)

Figure 4.19. Microprogrammed Control Unit



Name:

Notes on the Microprogrammed Control Unit:

- It's important to remember that a microprogrammed control unit works like a • system-in-miniature.
- Microinstructions are fetched, decoded, and executed in the same manner as regular instructions. • This extra level of instruction interpretation is what makes microprogrammed control slower than hardwired control.
- The advantages of microprogrammed control are that it can support very complcated ٠ instructions and only the microprogram needs to be changed if the instruction set changes (or an error is found).

<b>Revised Figure 4.21 Partial Microprogram</b>						
Part						
of	RTN		MicroOp	MicroOp		
Cycle	(of MicroOp1)	µAddr	1	2	Jump	Dest
Fetch	MAR ← PC	0	01001	0000	0	0
	$MBR \leftarrow M[MAR]$	1	01100	0000	0	0
	IR ← MBR	2	00101	0000	0	0
	$PC \leftarrow PC + 1$	3	10000	0000	0	0
Decode	If ADD, Jump	4	10111	00110	1	1710
	If LOAD, Jump	5	10111	00010	1	
("Jump	If STORE, Jump	6	10111	00100	1	
Table")	If SKIPCOND, Jump	7	10111	10000	1	
	If SUBT, Jump	8	10111	01000	1	
	If JUMP, Jump	9	10111	10010	1	
	If ADDI, Jump	10	10111	10110	1	
	If CLEAR, Jump	11	10111	10100	1	
	If JNS, Jump	12	10111	00000	1	
	If JUMPI, Jump	13	10111	11000	1	
	If INPUT, Jump	14	10111	01010	1	
	If OUTPUT, Jump	15	10111	01100	1	
	If HALT, Jump	16				
Execute ADD	MAR ← IR[11-0]	17	00111	00000	0	0
	MBR ← M[MAR]	18	01100	00000	0	0
	AC ← AC + MBR	19	00011	00000	1	0
Execute LOAD	MAR ← IR[11-0]	20				
	MBR ← M[MAR]	21				
	AC ← MBR	22				
Execute STORE	MAR ← IR[11-0]	23				
	MBR ← AC	24				
	M[MAR] ← MBR	25				
Execute SKIPCOND		26				
		27				
		28				
		29				
		30				
		31				
		32				
		33				

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## Revised Figure 4.21 Partial Microprogram